





## **RCJA OnStage Novice Performance Scoresheet** Team Name:

Category	Descriptor									
HARDWARE	Robots complete, sound and are working for the entire performance (4)									
	3-4: all robot(s) work	work 2: robot(s) have minor errors			ve major	0: no performance possible	1			
	errors errors possible   All robots play a role in the performance (5)									
	4-5: all powered objects	0: all powered objects								
	have a role	object	has no role	have no role have no role						
	Interaction betwee	n robo	t and other no	n-robot co	mponents	(3)				
	3: multiple interactions	2: som	e interactions	1: limited interactions at		0: no interactions				
	between range of components			limited points performance	; in					
	Robots demonstrate moving components fit for the performance (3)									
	3: multiple moving 2: at least one 1: functional rolling base 0: no functional									
	components beyond a		nent beyond	,,,.,		movement				
	rolling base	rolling					8			
ENGINEERING	Robot appearance complimented the performance (5)									
	5-4: well-coordinated		ostly coordinated	1: appearance	e and	0: no obvious link				
	robot appearance and performance		rance and ion paid to	performance theme/concept loosely		between appearance and performance				
	theme/concept		/concept	linked	bi loosely	una perjornance				
	Evidence of working communication between robots through interaction (3)									
	3: multiple Interactions		ral clear	1: very few op	-					
	throughout the		tions within the	to interact within		interactions				
	performance both visible and clear	perfor	mance	performance						
INNOVATION		domor	estrato rick (6)				12			
INNOVATION	Robot movements demonstrate risk (6)       5-6: Multiple, varying     3-4: Several risks with     1-2: At least one risk taken     0: no risks evident									
	risks demonstrated	some v		by moving close to edge,		o. no naka evident				
	throughout the		strated within the	risking balance etc.						
	performance performance									
	Robots move in a synchronised/themed manner (6)									
	5-6: movement of robots was purposeful,	3-4: movement of robots was coordinated and		1-2: movement of robots 0:no coordin indicated some evident		0:no coordination				
	coordinated and suitable	suitabl		coordination		evident				
CREATIVITY	The performance is stimulating and artistic (10)									
	8-10: Engaging, 5-7: mostly engaging, 1-4: Inconsistent, lacking 0: no performance									
	purposeful, audience	audien	ce centred	purpose and focus		values visible				
	centred (2)									
	Performers were engaged in the performance (3)       3: Performers integral part of     1-2: Performers enhanced the     0: No humans performed during									
	performance	0j	performance through mover		performance					
	A clear concept/the	eme is								
	7-8: all aspects work									
	together towards a clear	as a cl	ear theme/concept	theme/concept		evident through				
	goal performance									
	Creative use of the	_					4			
	3-4: performance used whole stage in a variety		ormance used of the stage in a	1: performance used more than one part of the stage		0: static performance using set parts of the				
	of ways	creativ		than one part of the stage		stage				
DEDUCTIONS	Restarts (-1) (Maximum of 2 allowed)									
	Each unplanned human intervention (-1). (Maximum 2 point deduction)									
	Not applied if restart applied.									
	Robot outside stage (-1) (Maximum 4 point deduction)									
	Not applied if restart applied.									
	Exceeding allotted time: Performance ends immediately (-3) MAXIMUM SCORE = 60, MINIMUM SCORE = 0									
TOTAL	MAXIMUM SCORE =	= 60 <i>,</i> N	IINIMUM SCOF	ε = 0						







## RCJA OnStage Novice Interview Score Sheet

## Team Name:

Category	Descriptor	Descriptor							
HARDWARE	Design and construction new and unique for competition season (2)       2: new and unique design and     1: Some elements of design and     0: no elements new or unique.								
	construction developed for the competition season		construction newly developed, with some sourced or copied elements		copied previous models or sourced designs				
	Use of moving parts (2)								
	2: a range of moving parts that demonstrate multiple modes of movement 2: a range of moving parts 1: some use of moving parts 0: No moving parts beyo rolling base								
SOFTWARE	Programming language(s) clearly demonstrate knowledge and use of accepted								
	programming techniques and features (4)     3-4: Highly developed and clearly   1-2: some use of enhanced   0: basic elements of simple								
	demonstrated advanced us complex programming tech and features	e of	languages or features, techniques and/or functions						
	Concepts used to improve readability of code (4)								
	3-4: Coding concepts releve language, age and level im readability	ant to	1-2: Coding conce language, age an readability in son	epts relevant to d level improve	0: no evidence of any effort used to improve readability				
	Sensors used to enhance interaction between robot(s) and the environment								
	(stage, props, other robots) (4)								
	3-4: multiple sensors present that are all programmed and used in a purposeful manner		1-2: at least one sensor programmed and used in a purposeful manner		0: no use of program code to enable any sensors		1		
	Evidence of messaging between robot and other elements (2)								
	2: purposeful programmed messaging between robot and other robots, props or stage		1: some evidence of a programmed message between robot and another robot or prop or		0: no programmed messaging evident				
ENGINEERING	element stage element						6		
	Stable build (2)     2: robots are stable and well   1: robots have some stability   0: robots are unstable, or lack any								
	balanced		through good design and construction		designed stabilisation				
	Technically sophisticated concept (4)								
	3-4: overall theme/concept displays varied technical components to create a coherent performance		1-2: overall theme/concept has more than one technical component that contributes to the performance		0: performance is simple, without any technical complexity beyond a rolling base moving or a motor turning				
PRESENTATION	Students can clearly explain how their robot(s) work (3)								
	3: team members fully understand and can explain all aspects of their robots, programming and their	2: team members understand and can explain most aspects of their robots, programming and		1: team members can explain few aspects of their robots, programming or performance		0: students cannot explain how their robots or programming work			
	performance performance (2)						-		
	All team members involved throughout the interview (3)     3: all and multiple team   2: multiple team   1: evidence of   0: one team member								
	balanced contribution to interview answers	membe demons their co		contributions to interview or materials by more than one person		only contributes to interview and interview materials			
TECHNICAL	Demonstrates that the work on display is authentic (6)								
DESCRIPTION	Hardware development process clearly indicated (1)								
PAPER	Performance concept development clearly indicated (1)								
	Software development process clearly indicated (2)								
TOTAL	· · · · · · · · · · · · · · · · · · ·	- 1				/40			